

# Geometry and Dynamics of singular symplectic manifolds

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Symplectic Geometry	Poisson Geometry
$\omega$	$\Pi$
$\iota_{X_f}\omega = -df$	$X_f := \Pi(df, \cdot)$
one symplectic leaf	a symplectic foliation
Darboux theorem	Weinstein's splitting theorem
$\omega = \sum_{i=1}^n dx_i \wedge dy_i$	$\Pi = \sum_{i=1}^k \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial x_i} + \sum_{kl} \phi_{kl}(z) \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_l}$
$L_X\omega = 0$	$L_X\Pi = 0$
$H_{DR}^1(M) = \frac{\text{symplectic v.f}}{\text{Hamiltonian v.f}}$	$? = \frac{\text{Poisson v.f}}{\text{Hamiltonian v.f}}$
$H_{DR}^k(M)$ (cochains $\Omega^k(M)$ )	$? := H_{\Pi}^k(M)$ (cochains $\mathfrak{X}^m(M)$ )

- Weinstein's splitting theorem and normal form theorems.

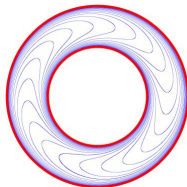


Figure: Alan Weinstein and Reeb foliation

- Poisson cohomology. Some computations.
- Compatible Poisson structures and commuting first integrals.

# Schouten Bracket of vector fields in local coordinates

- Case of vector fields,

$A = \sum_i a_i \frac{\partial}{\partial x_i}$  and  $B = \sum_i b_i \frac{\partial}{\partial x_i}$ . Then

$$[A, B] = \sum_i a_i \left( \sum_j \frac{\partial b_j}{\partial x_i} \frac{\partial}{\partial x_j} \right) - \sum_i b_i \left( \sum_j \frac{\partial a_j}{\partial x_i} \frac{\partial}{\partial x_j} \right)$$

- Re-denoting  $\frac{\partial}{\partial x_i}$  as  $\zeta_i$  (**“odd coordinates”**).

Then  $A = \sum_i a_i \zeta_i$  and  $B = \sum_i b_i \zeta_i$  and  $\zeta_i \zeta_j = -\zeta_j \zeta_i$ . Now we can reinterpret the bracket as,

$$[A, B] = \sum_i \frac{\partial A}{\partial \zeta_i} \frac{\partial B}{\partial x_i} - \sum_i \frac{\partial B}{\partial \zeta_i} \frac{\partial A}{\partial x_i}$$

# Schouten Bracket of multivector fields in local coordinates

We reproduce the same scheme for the case of multivector fields.

$$[A, B] = \sum_i \frac{\partial A}{\partial \zeta_i} \frac{\partial B}{\partial x_i} - (-1)^{(a-1)(b-1)} \sum_i \frac{\partial B}{\partial \zeta_i} \frac{\partial A}{\partial x_i}$$

is a  $(a + b - 1)$ -vector field.

where

$$A = \sum_{i_1 < \dots < i_a} A_{i_1, \dots, i_a} \frac{\partial}{\partial x_{i_1}} \wedge \dots \wedge \frac{\partial}{\partial x_{i_a}} = \sum_{i_1 < \dots < i_a} A_{i_1, \dots, i_a} \zeta_{i_1} \dots \zeta_{i_a}$$

and

$$B = \sum_{i_1 < \dots < i_b} B_{i_1, \dots, i_b} \frac{\partial}{\partial x_{i_1}} \wedge \dots \wedge \frac{\partial}{\partial x_{i_b}} = \sum_{i_1 < \dots < i_b} B_{i_1, \dots, i_b} \zeta_{i_1} \dots \zeta_{i_b}$$

with  $\frac{\partial(\zeta_{i_1} \dots \zeta_{i_p})}{\partial \zeta_{i_k}} := (-1)^{(p-k)} \eta_{i_1} \dots \widehat{\eta}_{i_k} \dots \eta_{i_{p-1}}$

## Theorem (Schouten-Nijenhuis)

The bracket defined by this formula satisfies,

*Graded anti-commutativity*  $[A, B] = -(-1)^{(a-1)(b-1)}[B, A]$ .

*Graded Leibniz rule*

$$[A, B \wedge C] = [A, B] \wedge C + (-1)^{(a-1)b} B \wedge [A, C]$$

*Graded Jacobi identity*

$$(-1)^{(a-1)(c-1)}[A, [B, C]] + (-1)^{(b-1)(a-1)}[B, [C, A]] + (-1)^{(c-1)(b-1)}[C, [A, B]] = 0$$

If  $X$  is a vector field then,  $[X, B] = L_X B$ .



- Space of cochains  $\mathfrak{X}^m(M)$ .
- Differential  $d_{\Pi}(A) := [\Pi, A]$ .
- Poisson cohomology

$$H_{\Pi}^k(M) := \frac{\ker d_{\Pi} : \mathfrak{X}^k(M) \longrightarrow \mathfrak{X}^{k+1}(M)}{\operatorname{Im} d_{\Pi} : \mathfrak{X}^{k-1}(M) \longrightarrow \mathfrak{X}^k(M)}$$

- Computation is difficult. It can be infinite-dimensional. Tools: Mayer-Vietoris, spectral sequences.
- Particular cases:  $(M, \Pi)$  symplectic  $H_{\Pi}^k(M) \cong H_{DR}^k(M)$ .
- $(M, \Pi)$   $b$ -Poisson,  $H_{\Pi}^k(M) \cong H_{DR}^k(M) \oplus H_{DR}^{k-1}(Z)$ .

- Hamiltonian vector fields  $X_f = -[\Pi, f]$  (1-coboundary).
- Poisson vector fields  $[\Pi, X] = -L_X\Pi = 0$  (1-cocycle).
- Poisson structures  $[\Pi, \Pi] = 0$  (2-cocycle).
- Compatible Poisson structures  $[\Pi_1, \Pi_2] = 0$  (2-cocycle).
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$$H_{\Pi}^1 = \frac{\text{Poisson vector fields}}{\text{Hamiltonian vector fields}}.$$



## Example 5: Cauchy-Riemann equations and Hamilton's equations

- Take a holomorphic function on  $F : \mathbb{C}^2 \rightarrow \mathbb{C}$  decompose it as  $F = G + iH$  with  $G, H : \mathbb{R}^4 \rightarrow \mathbb{R}$ .

**Cauchy-Riemann** equations for  $F$  in coordinates  $z_j = x_j + iy_j$ ,  $j = 1, 2$

$$\frac{\partial G}{\partial x_i} = \frac{\partial H}{\partial y_i}, \quad \frac{\partial G}{\partial y_i} = -\frac{\partial H}{\partial x_i}$$

- Reinterpret these equations as the equality

$$\{G, \cdot\}_0 = \{H, \cdot\}_1 \quad \{H, \cdot\}_0 = -\{G, \cdot\}_1$$

with  $\{\cdot, \cdot\}_j$  the Poisson brackets associated to the real and imaginary part of the symplectic form  $\omega = dz_1 \wedge dz_2$  ( $\omega = \omega_0 + i\omega_1$ ).

- Check  $\{G, H\}_0 = 0$  and  $\{H, G\}_1 = 0$  (integrable system).

## Example 2: Determinants in $\mathbb{R}^3$

- **Dynamics:** Given two functions  $H, K \in C^\infty(\mathbb{R}^3)$ . Consider the system of differential equations:

$$(\dot{x}, \dot{y}, \dot{z}) = dH \wedge dK \quad (1)$$

$H$  and  $K$  are constants of motion (the flow lies on  $H = cte.$  and  $K = cte.$ )

- **Geometry:** Consider the brackets,

$$\{f, g\}_H := \det(df, dg, dH) \quad \{f, g\}_K := \det(df, dg, dK)$$

They are antisymmetric and satisfy Jacobi,

$$\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0.$$

The flow of the vector field

$$\{K, \cdot\}_H := \det(dK, \cdot, dH)$$

and  $\{-H, \cdot\}_K$  is given by the differential equation (1) and

$$\{H, K\}_H = 0, \quad \{H, K\}_K = 0$$